

A Multi-channel Smart Strain Sensor with IEEE 1451 Protocol

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Esensors Inc.

23rd Annual Transducer Workshop

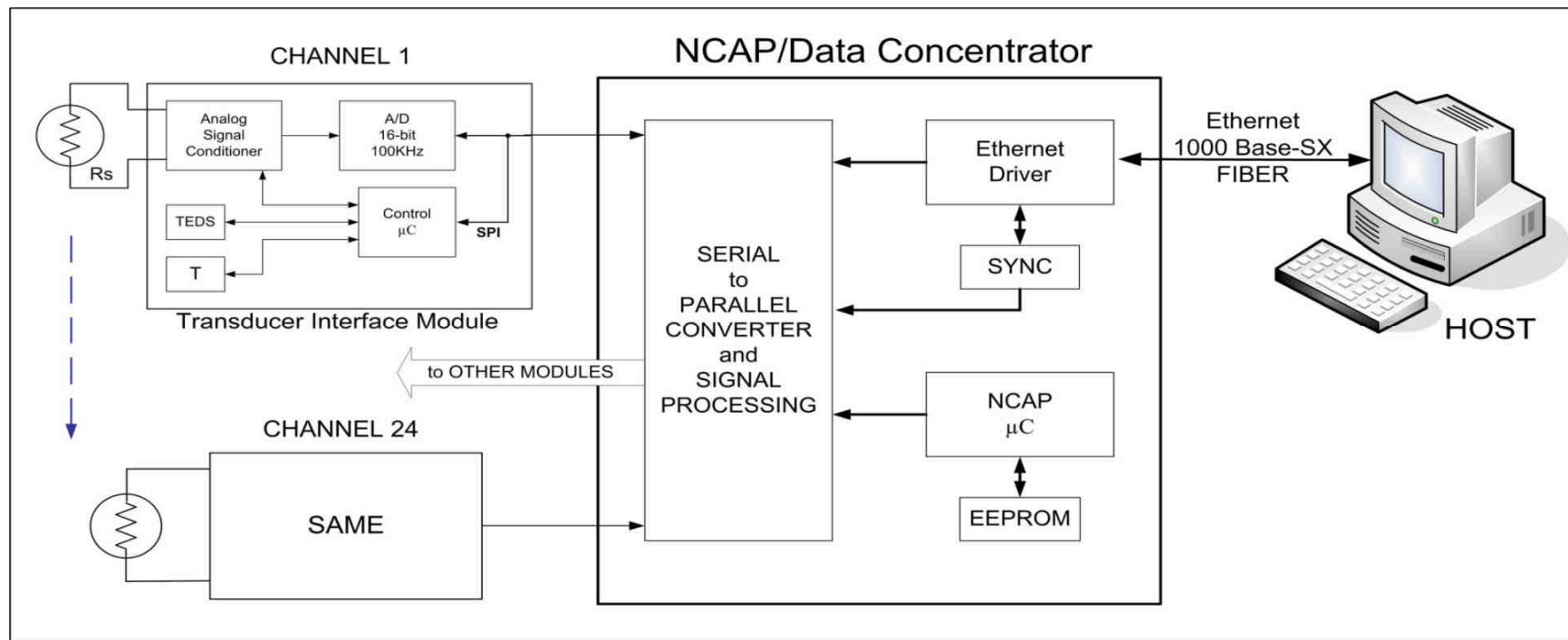
Buffalo NY, June 2008



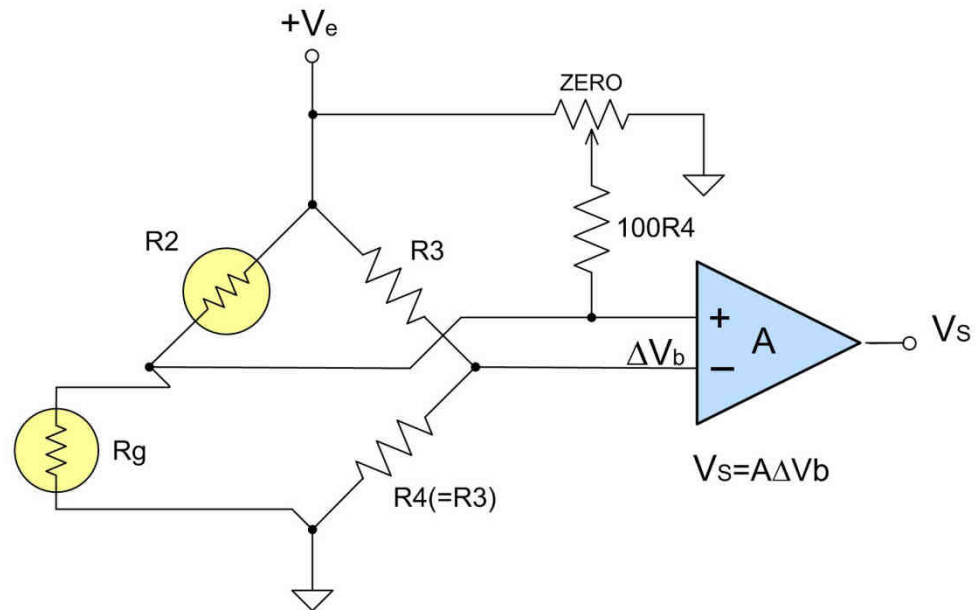
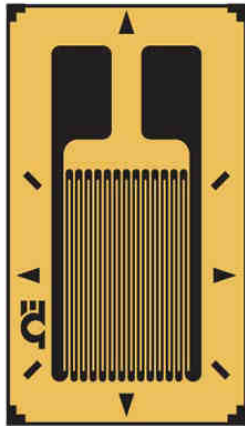
Project Goals₂

- Design & test high performance strain gage data acquisition system (up to 24-channel)
- Provide high speed real time data link
- Provide precision time stamp
- Use IEEE 1451 Protocol (emphasis of this presentation)

System Block Diagram



Basic Strain Gage Bridge



The bridge output, for one active element (1/4-bridge) is:

$$\Delta V = \frac{V_e \Delta R}{4R_o} = \frac{V_e G_f \epsilon}{4}$$

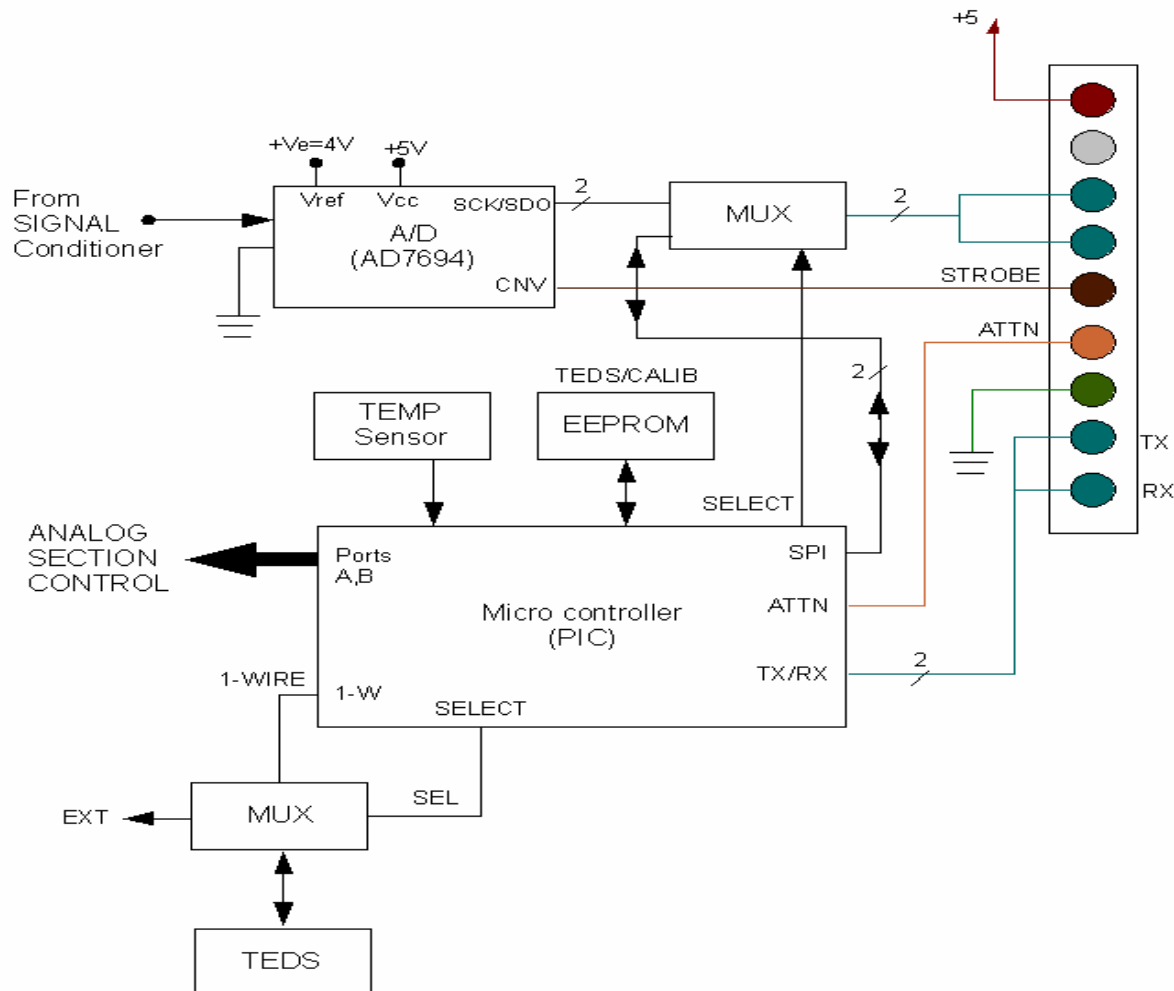
Strain Sensor with 1451



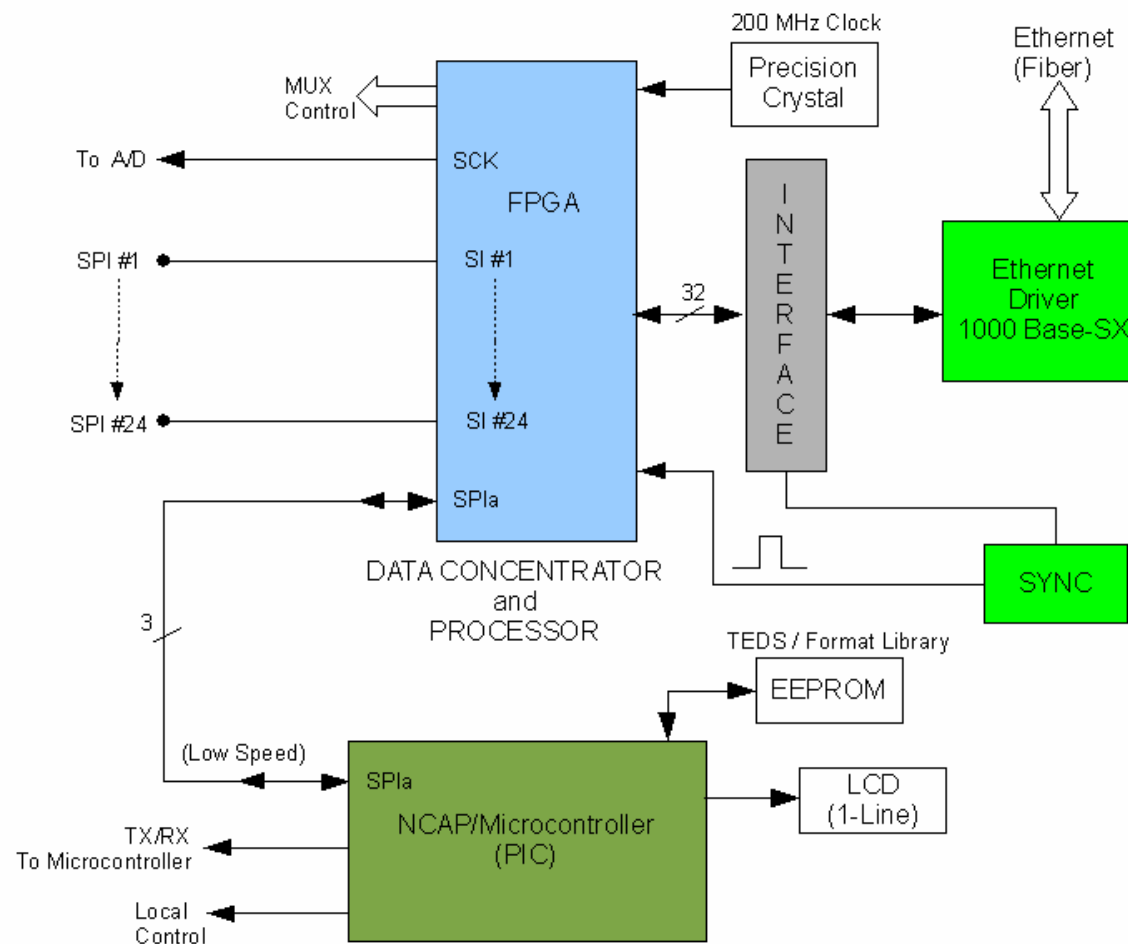
System Features

- ☐ Coarse and fine digitally controlled bridge zeros
- ☐ Full, half or quarter bridge
- ☐ Gain variable in x2 steps (digitally)
- ☐ Low noise, fast response amplifiers
- ☐ Adjustable high frequency break points
- ☐ AC or DC coupling
- ☐ Proper analog ground, bypass and shielding
- ☐ Transducer Electronic Data Sheet (TEDS)
- ☐ Expandable to various sensor technologies

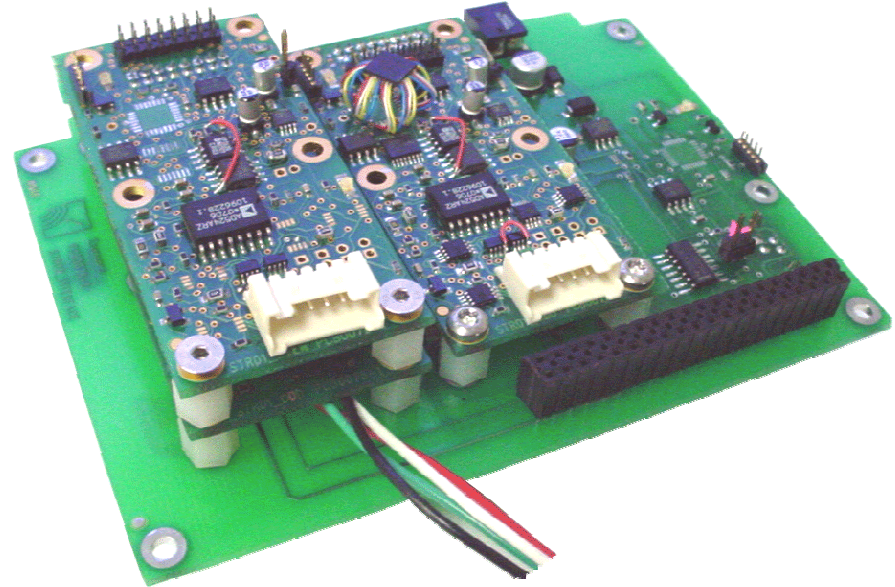
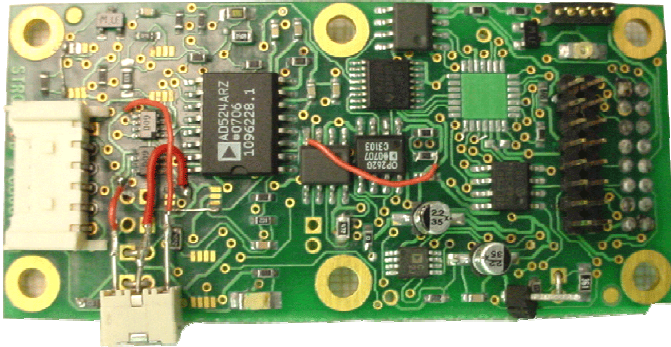
A/d and control section



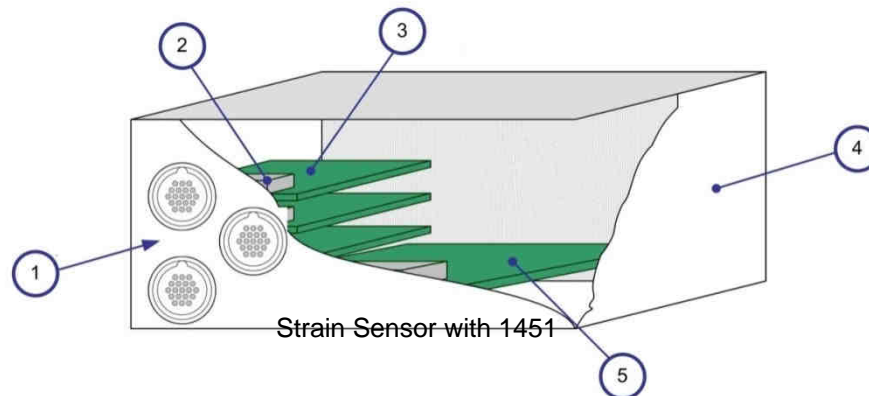
Signal assembly and reformatting



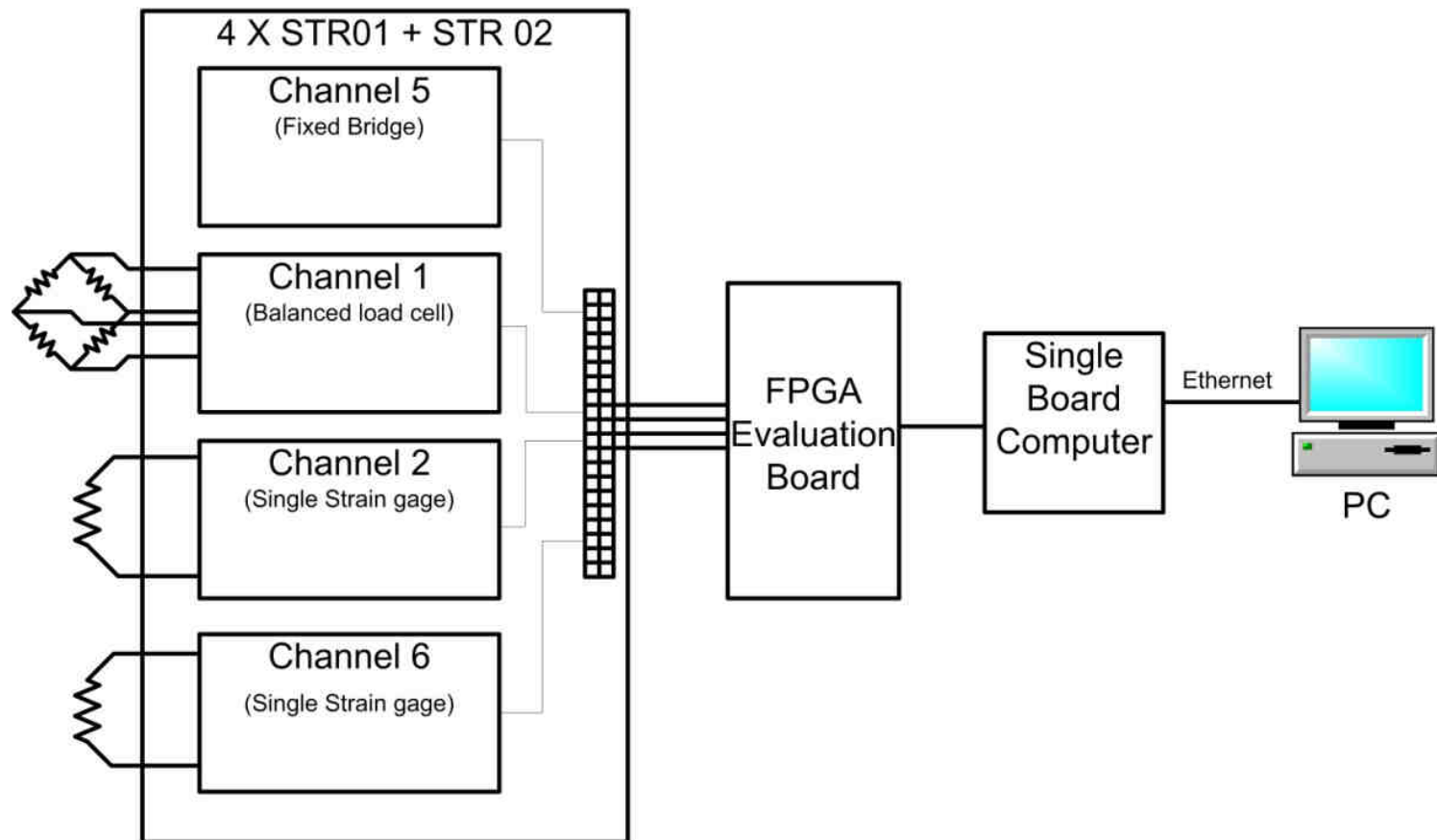
Circuit board realizations



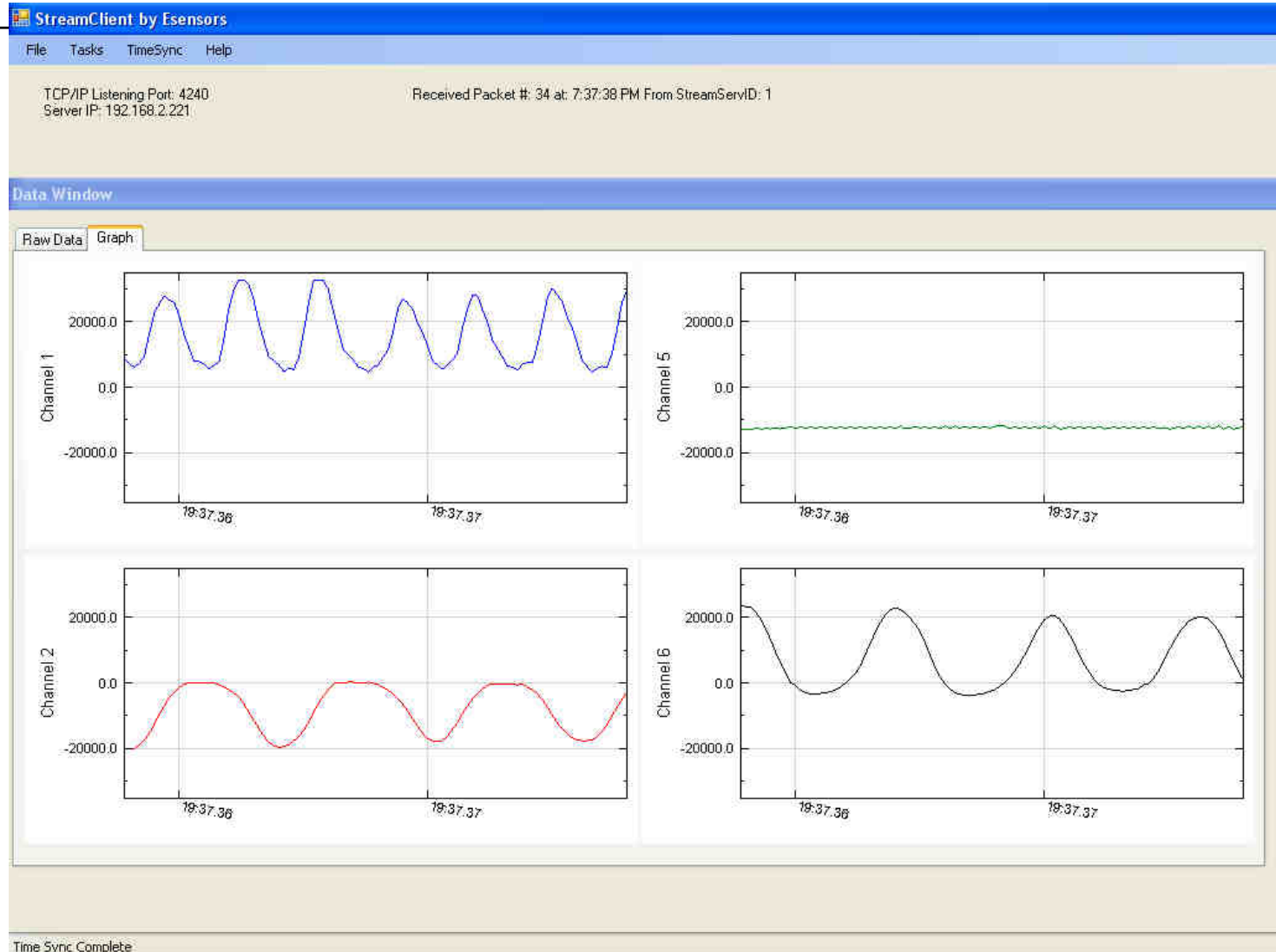
Signal conditioner
board stacking



Test setup



Test Results (analog)

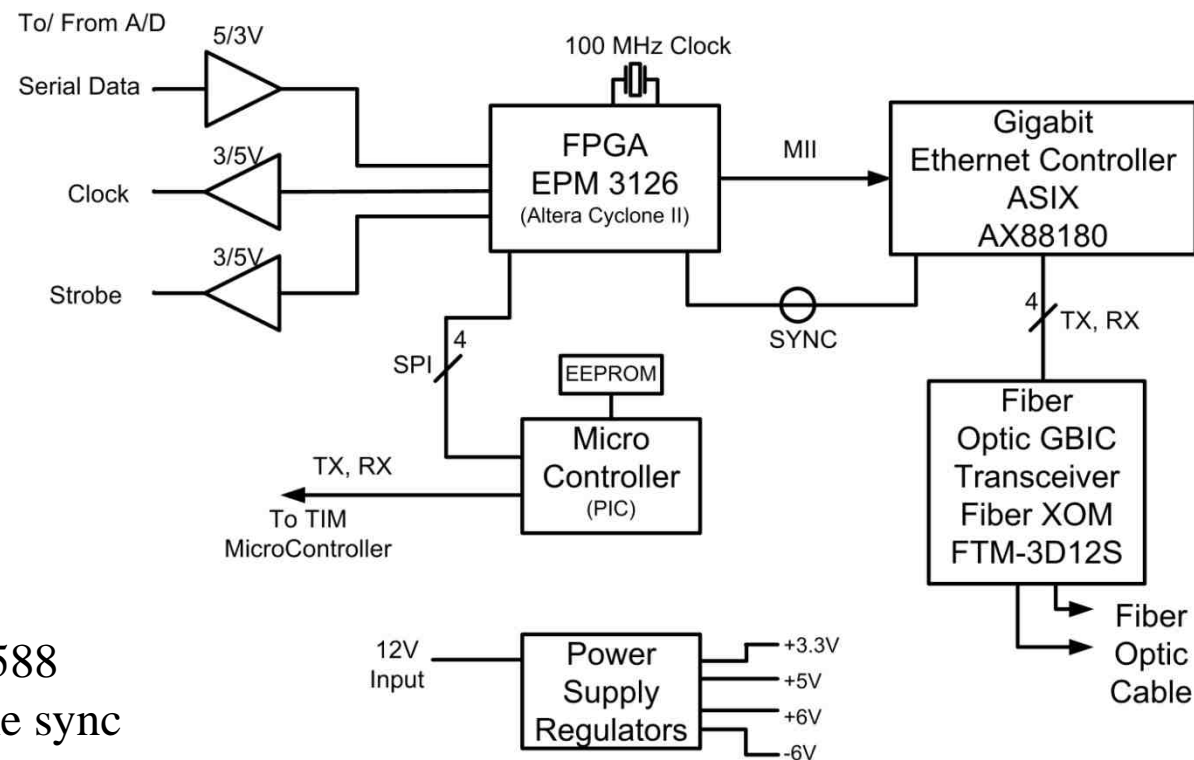


Example of Transmitted Data

The screenshot displays the StreamClient by Esensors application window. The title bar reads "StreamClient by Esensors". The menu bar includes "File", "Tasks", "TimeSync", and "Help". The main status area shows "TCP/IP Listening Port: 4240" and "Server IP: 192.168.2.221" on the left, and "Received Packet #: 66 at: 4:18:57 PM From StreamServID: 1" on the right. Below this is a "Data Window" section with two tabs: "Raw Data" (selected) and "Graph". The "Raw Data" tab displays a list of 20 received packets, each with its StreamServID, Channel, Time, and Payload.

StreamServID	Channel	Time	Payload
1	6	633292715127892410	18447
1	5	633292715127892410	17423
1	4	633292715127892410	3711
1	3	633292715127892410	-31202
1	2	633292715127892410	20287
1	1	633292715127892410	-18465
1	8	633292715128012470	16399
1	7	633292715128012470	22559
1	6	633292715128012470	18447
1	5	633292715128012470	18239
1	4	633292715128012470	3631
1	3	633292715128012470	-29180
1	2	633292715128012470	20335
1	1	633292715128012470	-16836
1	8	633292715128092470	18659
1	7	633292715128092470	22755
1	6	633292715128092470	18659
1	5	633292715128092470	18303
1	4	633292715128092470	8143
1	3	633292715128092470	-29568
1	2	633292715128092470	24519
1	1	633292715128092470	-16386

Proposed 24-channel system



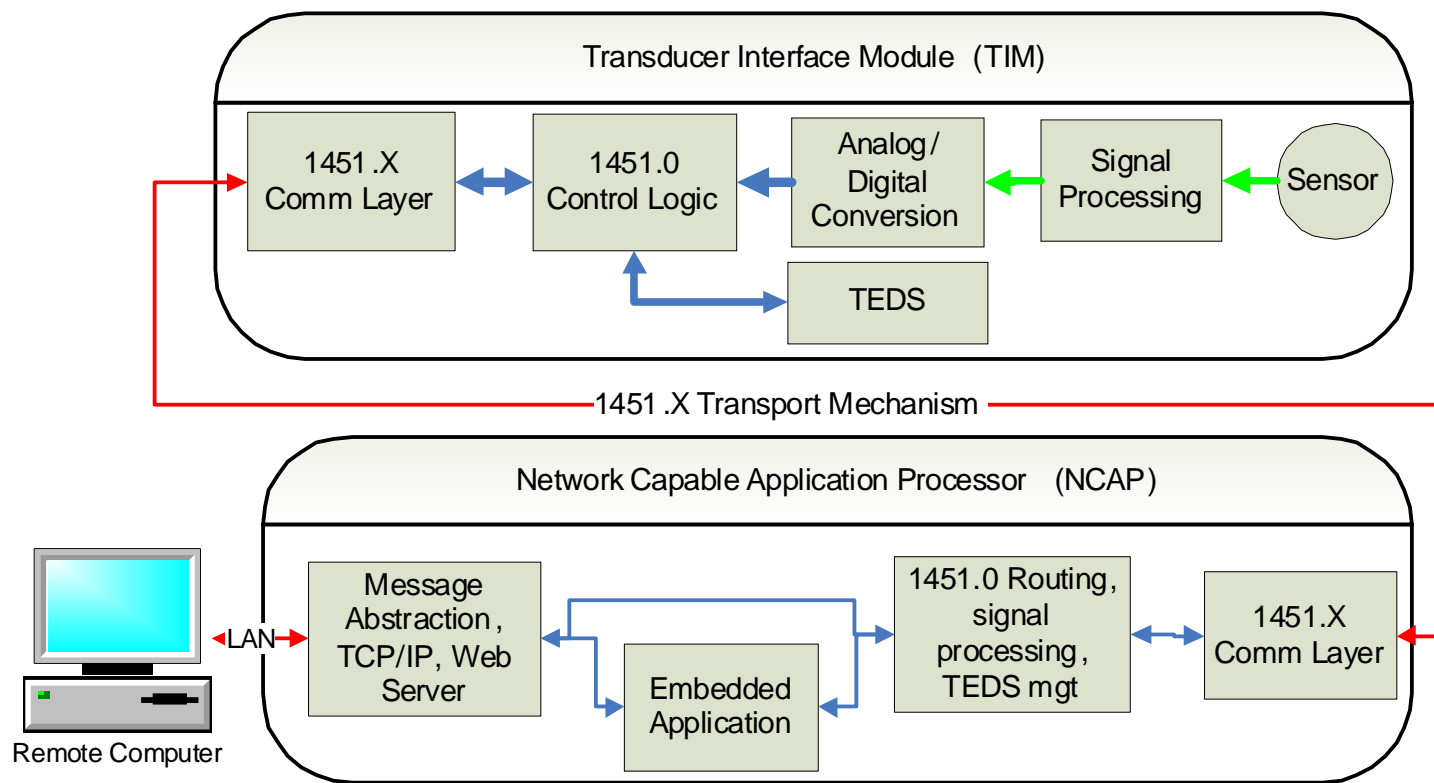
Uses IEEE 1588
concepts for time sync



Use of IEEE 1451 Universal Sensor Format

- ❑ Provide full, unambiguous data transfer format
- ❑ Allow mix of multiple sensors
- ❑ Automatic configuration (plug and play)
- ❑ Transducer Electronic Data Sheet (TEDS)
- ❑ Provide time synchronization option

A review of the IEEE 1451 Smart Transducer Concept



Strain Sensor with 1451

IEEE 1451 Advantages

- Many operating modes
(buffered, no-buffer, grouped sensors, timestamps, timed data, streaming ...)
- Extensive units, linearization and calibration options
- Multiple timing and data block size constraints handled.
- Compatible with most wired and wireless sensor buses and networks (point-to-point, mesh, TIM-to-TIM, mixed networks).
- Comprehensive enough to cover nearly all sensors and actuators in use today (not 20/80% approach)
- Efficient binary protocol (especially suitable for wireless)
- Standard is 400+ pages for basic part, over 1500 page total

Status of Various Parts of IEEE 1451

<input type="checkbox"/> 1451.0 – Basic data/TEDS format	Done (2007)
<input type="checkbox"/> 1451.1 – NCAP/Computer Interface	Done (1999)*
<input type="checkbox"/> 1451.2 – RS-232	Done (1997)*
<input type="checkbox"/> 1451.3 – Wired Multi-drop	Done (2002)*
<input type="checkbox"/> 1451.4 – TEDS Only	Done (2005)
<input type="checkbox"/> 1451.5 – Wireless (WiFi, Zigbee, etc)	Done (2007)
<input type="checkbox"/> 1451.6 – CAN Bus	In process
<input type="checkbox"/> 1451.7 – RFID	In process

* Needs revision



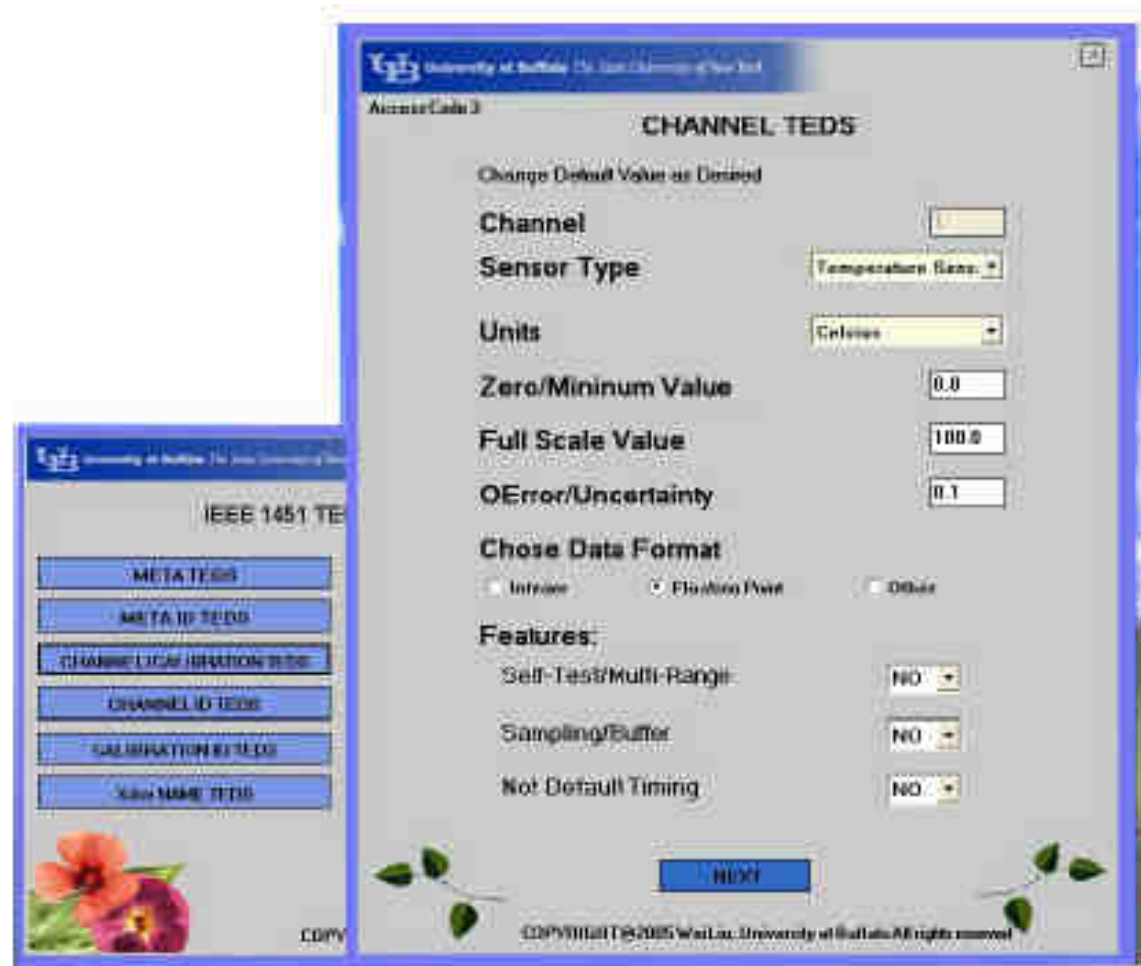
IEEE 1451.0 (Dot 0) TEDS Format

- Required TEDS [Memory block with defined format]
 - MetaTEDS
 - Channel TEDS
 - Calibration TEDS (unless SI units)
 - Xdr-name TEDS
 - Phy TEDS
 - Also optional TEDS

- Data Transmission [specific octet format]
 - TEDS/Status requests
 - Triggering and configuration
 - Sensor read commands and data return
 - Actuator write commands and data sending

TEDS Compiler

- Part of Ph. D. thesis of
Wai Liu
(Univ. at Buffalo)



Standard Transducer Units

(binary format)

SI Based Units

Base Quantity	Name	Unit Symbol
Length	meter	m
Mass	kilogram	kg
Time	second	s
Electric current	ampere	A
Thermodynamic temperature	Kelvin	K
Amount of substance	mole	mol
Luminous intensity	candela	cd

Field	Description	Data Type	Number of octets
1	Physical units interpretation	UInt8	1
2	$(2 * \text{<exponent of radians>}) + 128$	UInt8	1
3	$(2 * \text{<exponent of steradians>}) + 128$	UInt8	1
4	$(2 * \text{<exponent of meters>}) + 128$	UInt8	1
5	$(2 * \text{<exponent of kilograms>}) + 128$	UInt8	1
6	$(2 * \text{<exponent of seconds>}) + 128$	UInt8	1
7	$(2 * \text{<exponent of amperes>}) + 128$	UInt8	1
8	$(2 * \text{<exponent of kelvins>}) + 128$	UInt8	1
9	$(2 * \text{<exponent of moles>}) + 128$	UInt8	1
10	$(2 * \text{<exponent of candelas>}) + 128$	UInt8	1

Dot 0 Command/Response Structure

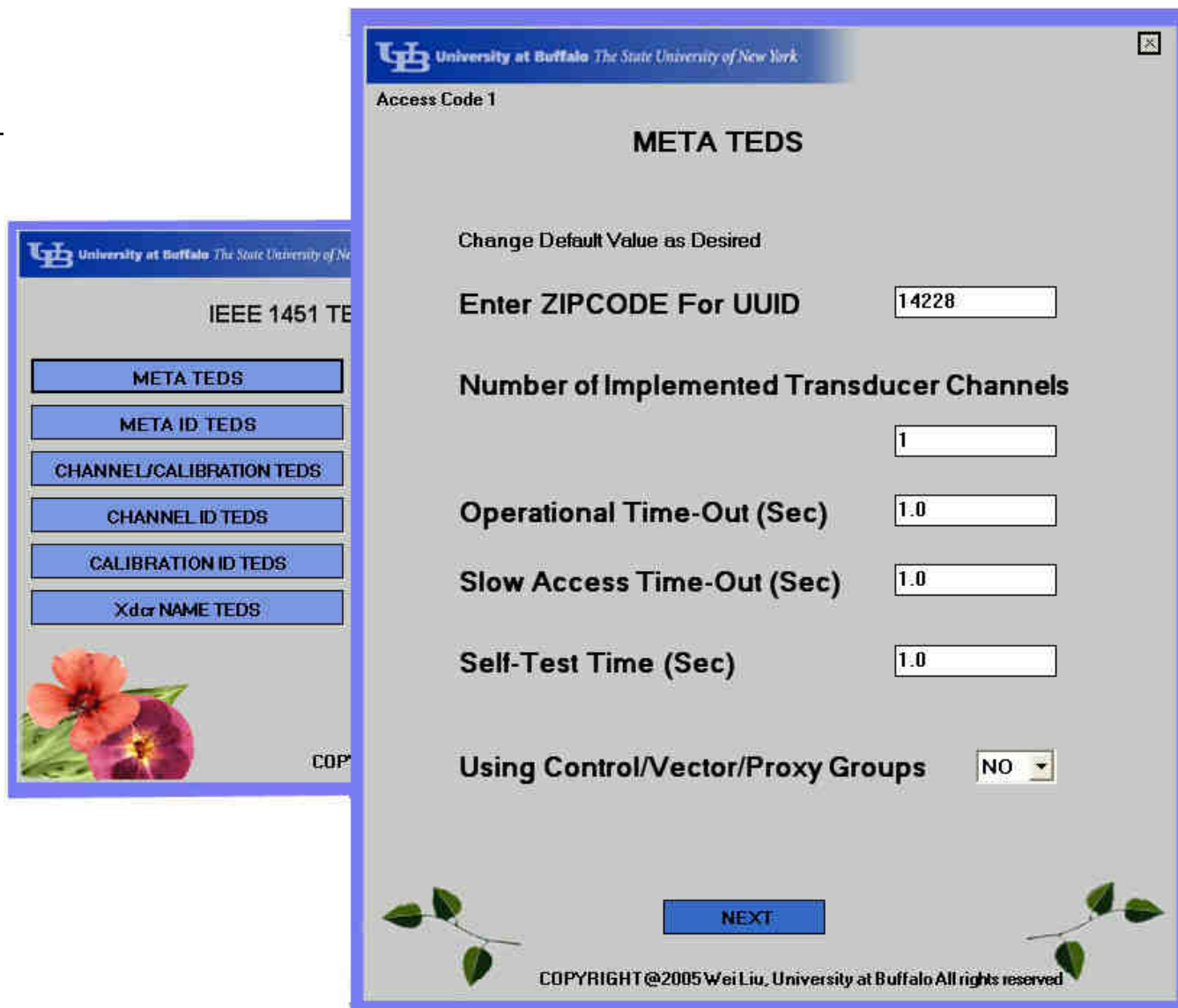
Byte Number	Description
1	Destination Transducer Channel Number (Most significant byte)
2	Destination Transducer Channel Number (Least significant byte)
3	Command Class
4	Command Function
5	Length (Most significant byte)
6	Length (Least significant byte)
7-N	Command dependent bytes

NCAP Command Message Structure

Byte Number	Description
1	Success/Fail Flag
2	Length (Most significant byte)
3	Length (Least significant byte)
4-N	Reply dependent bytes

TIM Reply Message Structure

Meta-TEDS Writer Screen



The screenshot displays the Meta-TEDS Writer interface. On the left is a sidebar with a menu of options: META TEDS, META ID TEDS, CHANNEL/CALIBRATION TEDS, CHANNEL ID TEDS, CALIBRATION ID TEDS, and Xdc NAME TEDS. The main window is titled 'META TEDS' and includes a header with the University at Buffalo logo and 'Access Code 1'. Below the title, it says 'Change Default Value as Desired'. The form contains several input fields: 'Enter ZIPCODE For UUID' with the value '14228', 'Number of Implemented Transducer Channels' with '1', 'Operational Time-Out (Sec)' with '1.0', 'Slow Access Time-Out (Sec)' with '1.0', and 'Self-Test Time (Sec)' with '1.0'. There is also a dropdown menu for 'Using Control/Vector/Proxy Groups' set to 'NO'. At the bottom, there is a 'NEXT' button and a copyright notice: 'COPYRIGHT ©2005 Wei Liu, University at Buffalo All rights reserved'. A small image of flowers is visible in the bottom left corner of the sidebar.

University at Buffalo The State University of New York

Access Code 1

META TEDS

Change Default Value as Desired

Enter ZIPCODE For UUID

Number of Implemented Transducer Channels

Operational Time-Out (Sec)

Slow Access Time-Out (Sec)

Self-Test Time (Sec)

Using Control/Vector/Proxy Groups

NEXT

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Channel/Calibration TEDS (for linear sensors)

University at Buffalo The State University of New York

Access Code 3

CHANNEL TEDS

Change Default Value as Desired

Channel

Sensor Type

Units

Zero/Minimum Value

Full Scale Value

Offset/Uncertainty

Chose Data Format

☐ Integer ☒ Floating Point ☐ Other

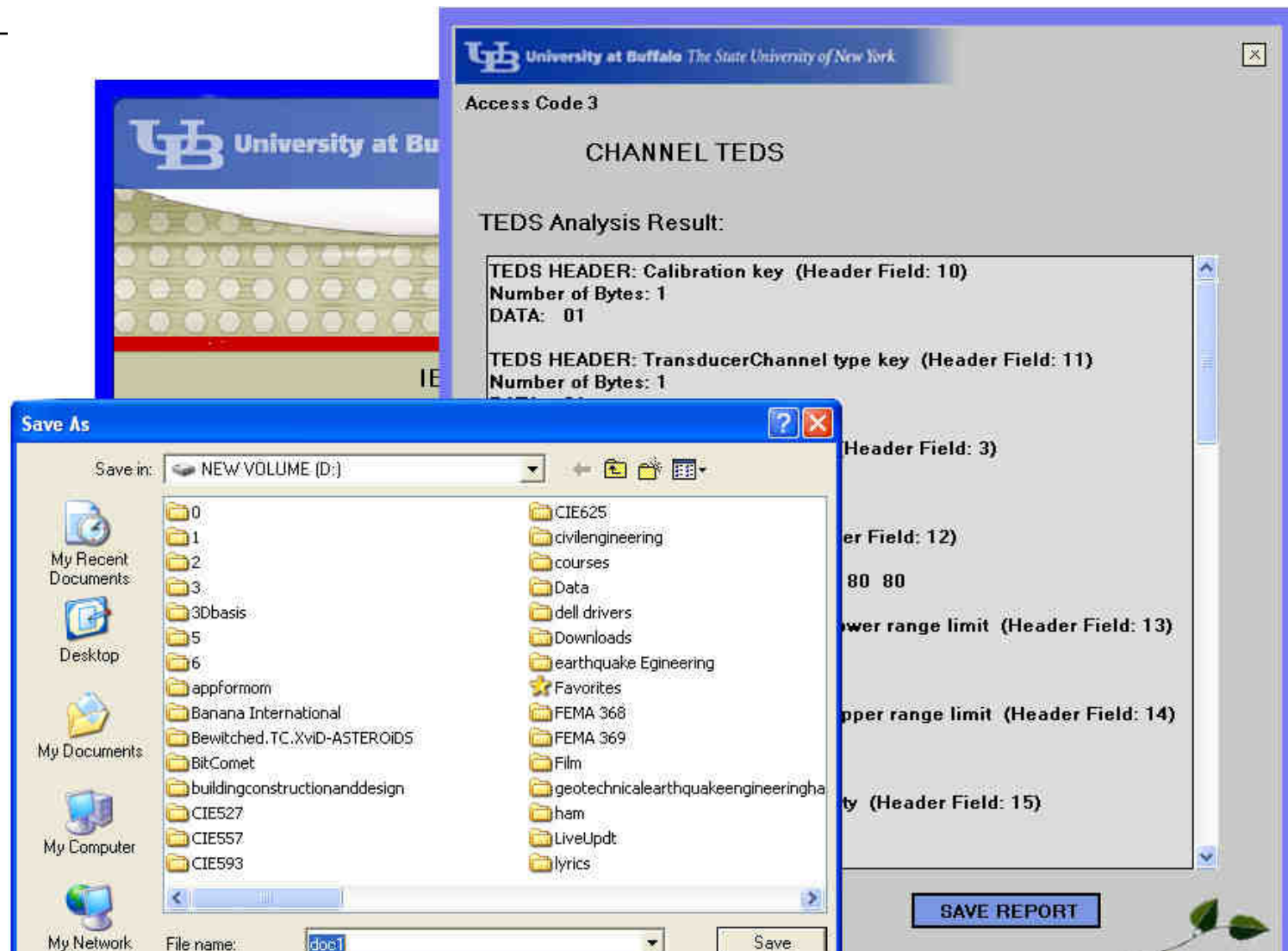
Features:

Self-Test/Multi-Range

Sampling/Buffer

Not Default Timing

TEDS Reader

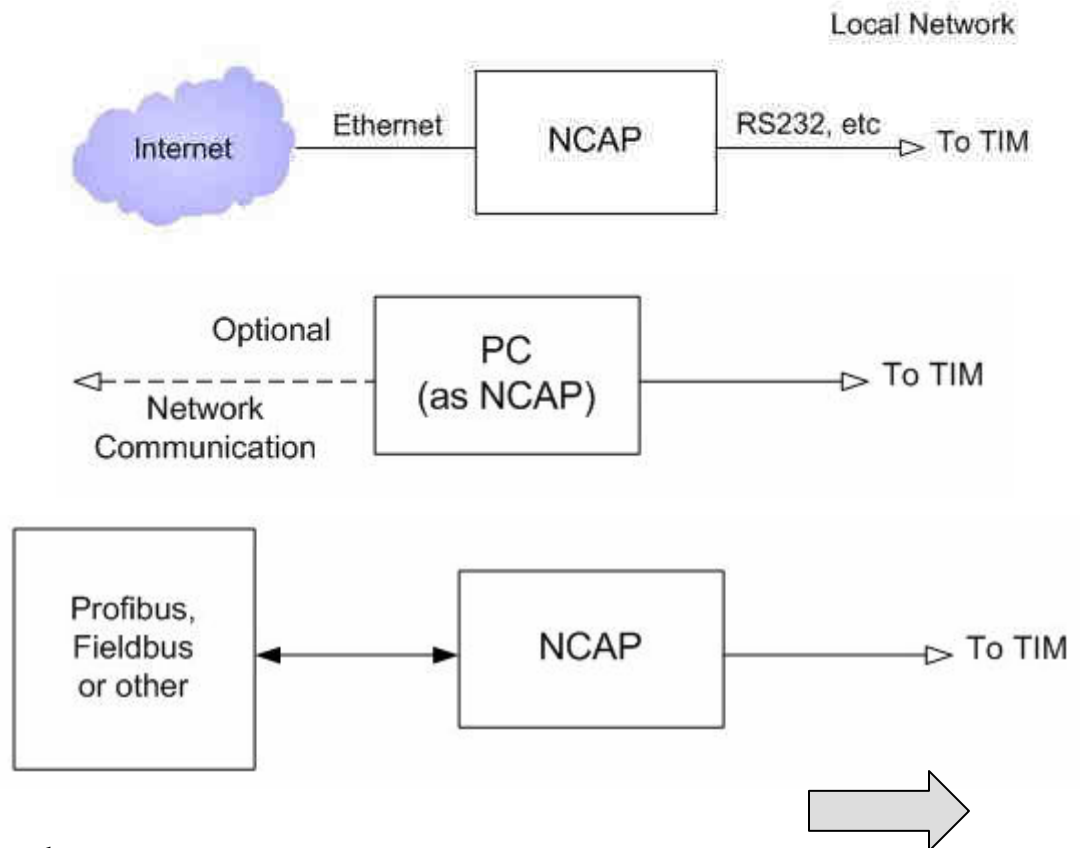


Network side (NCAP) options (wired)

☐ Internet/Ethernet

☐ PC Readout

☐ Industrial
network

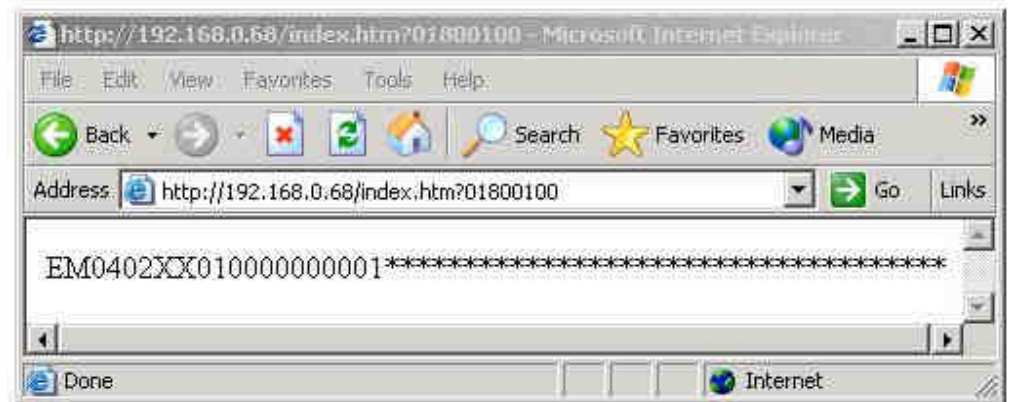


All use Dot 0 protocol

Strain Sensor with 1451

Data Readout Examples (via Internet)

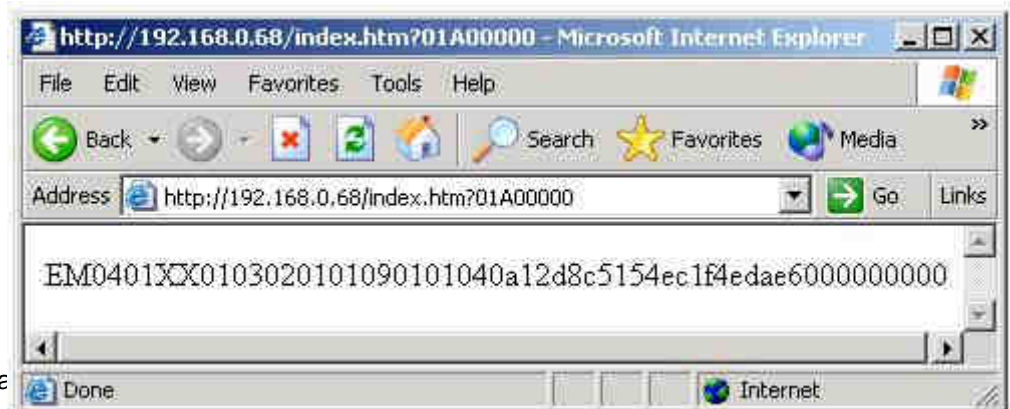
- Sensor data converted to ASCII for display



- TEDS data is displayed in hexadecimal form



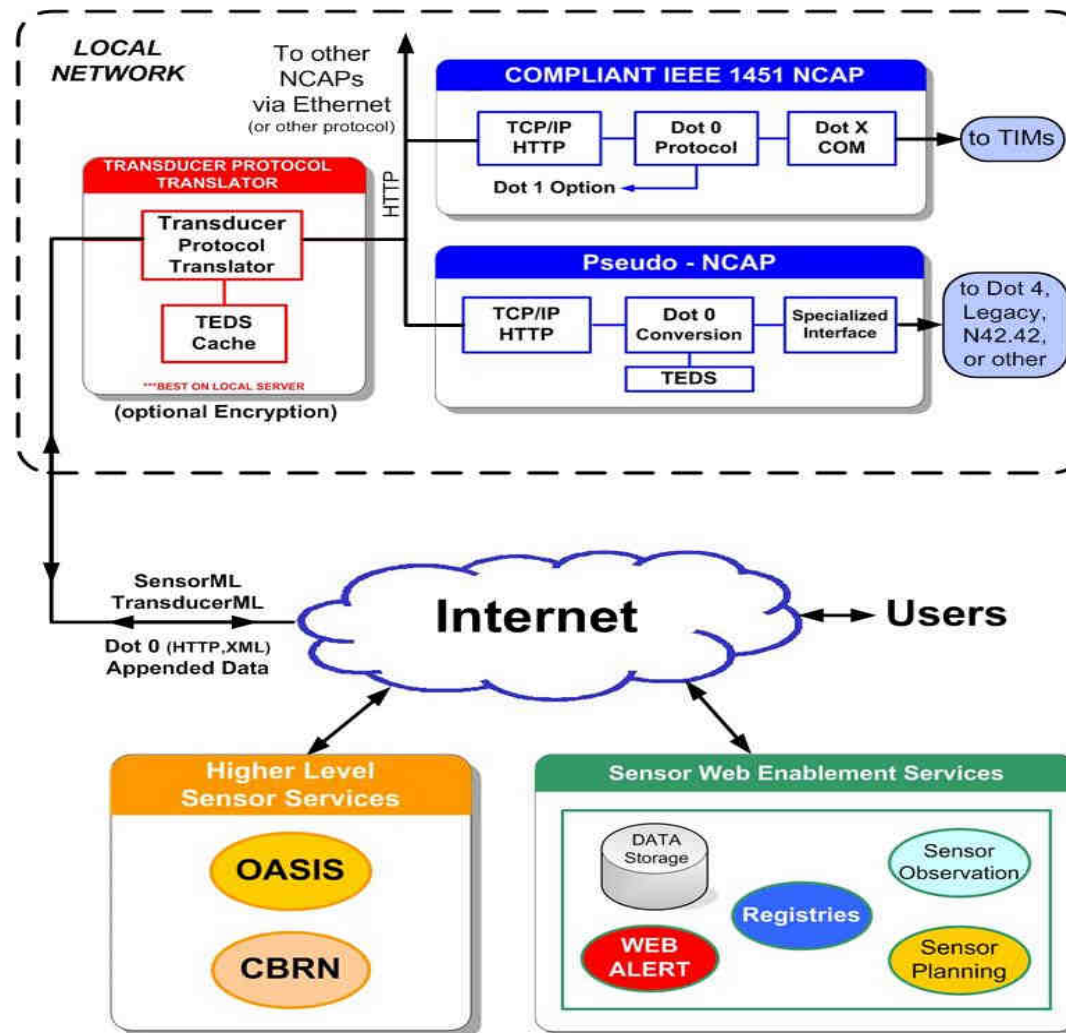
Str



IEEE 1451 as a Universal Digital Sensor Base Format

- Specialized networks can handle only a limited number of sensor types or uses non-compact format
 - 1451 is much superior at the sensor end
- Most applications require individualized displays or graphical user interfaces – 1451 is a fixed format and poorly suited at the user end
- Network oriented applications prefer XML or similar formats which are convenient, but are too verbose at the sensor end
- 1451 at the sensor end (Sensor Fusion level 0) combined with translators is the best solution.

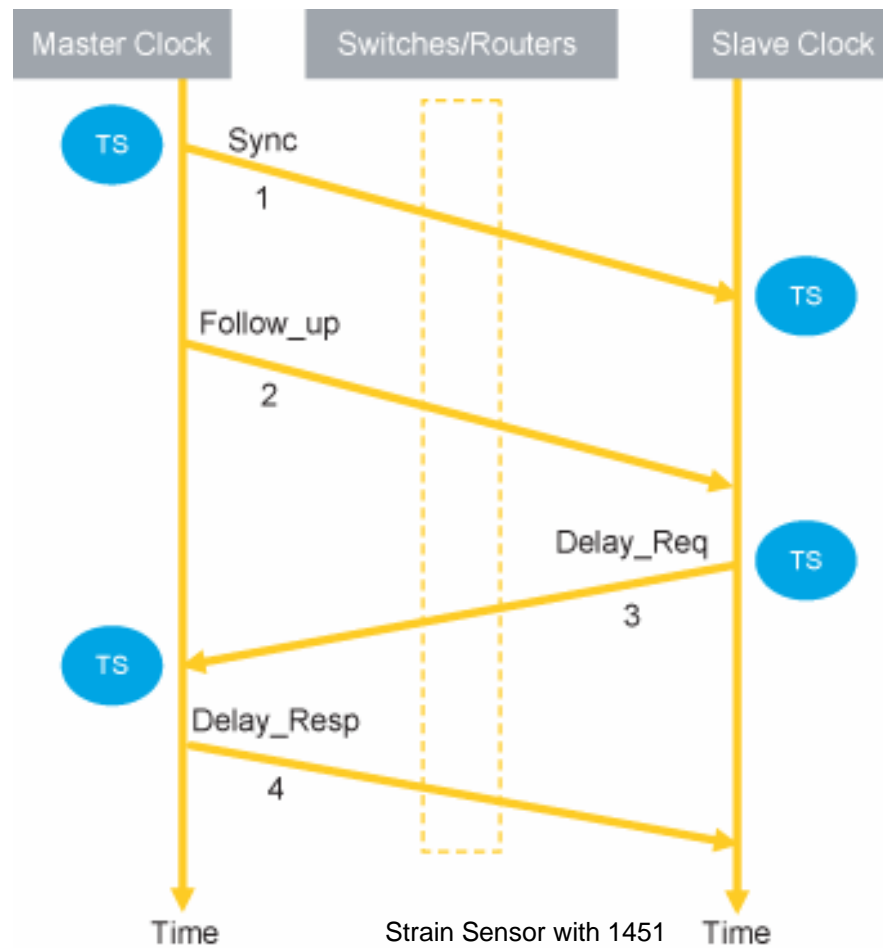
Harmonization of IEEE 1451 with Internet sensor standards



Future Prospects for IEEE 1451

- There has been little interest in previous parts of IEEE 1451 (Dots 2, 1 & 3), except for Dot 4 in certain areas.
- The basic Dot 0 (and Dot 5) are more carefully composed and thus likely to be accepted.
- The compiler may answer the complexity issue but still implementation of any full-featured standard will be difficult.
- The US government may mandate a sensor data standard and the NIST-supported IEEE 1451 is the most recognized candidate.
- The sensor industry, especially the wireless network sector, must recognize the business advantages of a single sensor data standard.

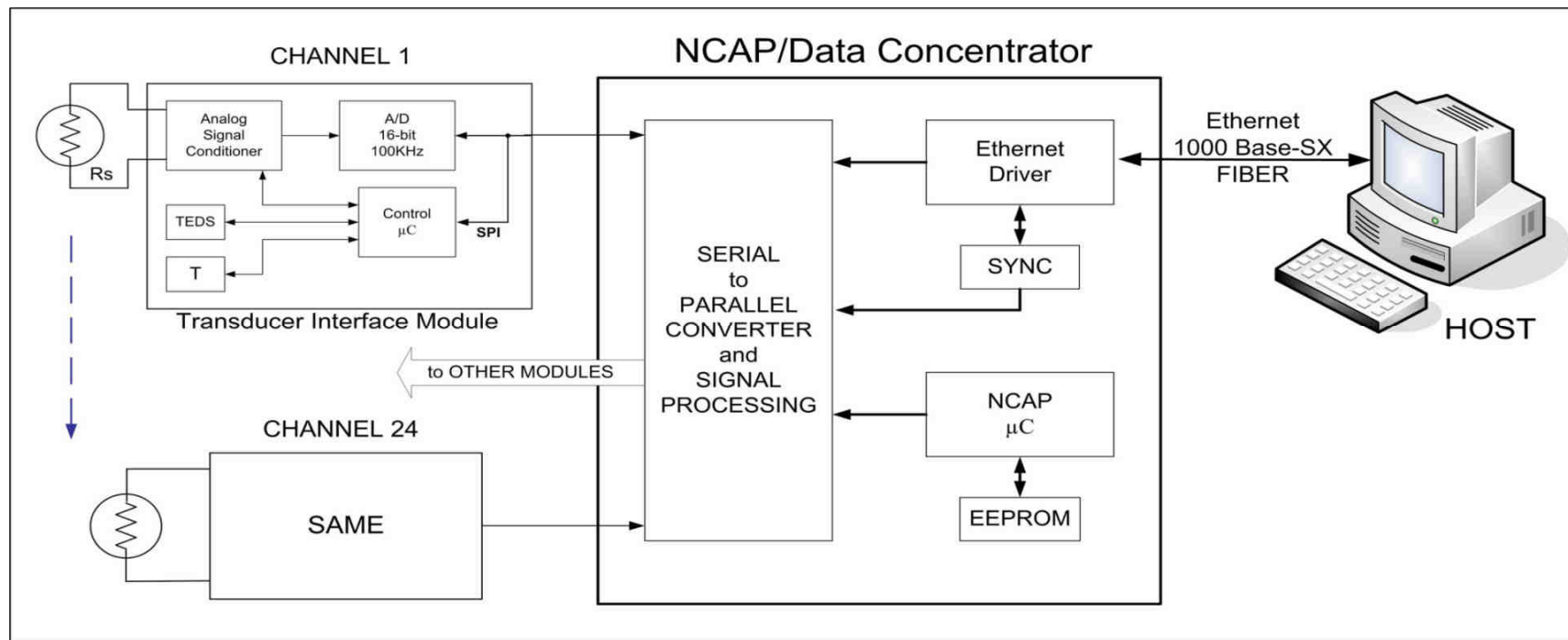
Time Synchronization



Based on IEEE 1588

Recall

System Block Diagram





Applications

- ❑ Especially suitable for mix of networked sensors
- ❑ Provides basis for plug and play
- ❑ Prov
- ❑ Present system easily adapted for:
 - strain
 - force
 - pressure
 - temperature
 - acceleration



Acknowledgements

- ❑ Supported by Arnold Air Force Base (SBIR, Ph I)
- ❑ Participating engineers
 - A. Cherian
 - K. Sielski
 - K. Chow
 - J. George
 - W. Liu



Summary

- High performance strain gage data acquisition system designed and tested
- Provides high speed real time data link
- Provides precision time stamp
- Uses IEEE 1451 Protocol
(which was discussed in some detail)

Contact: designer@eesensors.com



End

□ Backup Slides Follow



www.eesensors.com



Harmonization Meeting Summary

(Held at NIST quarterly)

- ❑ 25-50 attendees, mostly government
- ❑ DOD, DHS, DJ, DS represented (also NASA subcontractor)
- ❑ All working under directives to implement standards
- ❑ DHS new directive requires new sensors to use existing open standards if available (not proprietary or invent new)
- ❑ DOD joint task group working on standards and expects to support test bed. Possible FY'10 requirement.
- ❑ Several test beds involving IEEE 1451 started (Esensors has some part in all).



Wireless Sensor Networks

- ❑ Currently fashionable in academic and VC circles
- ❑ Recently available low-cost, high performance RF transceiver chips greatly simplify design
- ❑ Improvements in embedded microcomputers and smart sensor design also make wireless sensors much more practical now
- ❑ Can be lower cost and easier to use than wired sensors
- ❑ Point-to-point and mesh protocols available.
- ❑ Specialized sensor networks (e.g. Zigbee) much more efficient for wireless sensors, especially battery operated.
- ❑ Lack of standards inhibiting growth of industry.



Future of Networked Sensors

- ❑ Computer-based monitoring and control applications are increasing in commercial, industrial and military sectors.
- ❑ Networked, and often wireless, sensors offer performance and cost advantages over traditional methods.
- ❑ Wider use of networked sensors is inhibited by lack of standards (especially National scale networks, wireless and multi-vendor, long-term installations).
- ❑ I expect sensor standard and harmonization efforts to succeed within 2 to 5 years and Federal Agencies (DHS, DOD; NASA) to favor IEEE 1451.



IEEE 451 TIM Compliance Tester

- ❑ TIM (Transducer Interface Module) is most complex and done by sensor design engineers
(TIM tester can be used by the few NCAP designers)
- ❑ Tester verifies compliance of a TIM to IEEE 1451.0 (Dot 0) protocol
- ❑ Focus is on TEDS checking and data transfer format
- ❑ Physical device compliance not checked (part of other standards, e.g. RS485, Bluetooth)
- ❑ Tester uses serial bus (RS232)
- ❑ Testing may be done by Internet

TEDS Format

- General format for each TEDS section:

Field	Description	Data Type	Number of Bytes
-----	TEDS Length	UInt32	4 bytes
1 to N	Data Block	Variable	Variable
-----	Checksum	UInt16	2 bytes

- Primary TEDS Table format for each data block.

Type-Length-value (TLV)

Example: 01 02 A3 04

Field type is 1, Length is 2 bytes, field value is “A304” hex

- Field example: Meta-TEDS (TEDS # 1)

13: Number of Implemented Transducer Channels (default=1)